

PHYSICS INFORMED GUIDED DIFFUSION FOR ACCELERATED MULTI-PARAMETRIC MRI RECONSTRUCTION

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MOTIVATION

Reconstruction of high quality multiparametric MRI e.g., Magnetic Resonance Fingerprinting (MRF)¹ from highly-accelerated acquisitions.

Challenges: Severely aliased/corrupted inputs / high computational cost of Denoising Diffusion Models (DDM^{2,3,4}) / adherence to the acquisition physics.

MRF-DiPh

➤ MRF reconstruction problem:

$$\arg \min_{\mathbf{x} \in \mathcal{B}} f(\mathbf{x}) + \lambda h(\mathbf{x}) \quad (1)$$

- $\mathbf{x}$: MRF images to reconstruct
- $f(\mathbf{x}) = \|\mathbf{y} - \mathbf{A}\mathbf{x}\|_2^2$ k-space consistency w/ measurements $\mathbf{y}$, given forward operator $\mathbf{A}$
- $h(\mathbf{x})$ regularizer/image prior
- $\mathcal{B} := \{\mathbf{x} \text{ s.t. } \mathbf{x} = \boldsymbol{\rho} \cdot D(\mathbf{T1}, \mathbf{T2})\}$ Bloch model consistency w/ tissue maps $\mathbf{T1}, \mathbf{T2}$ and proton density ($\boldsymbol{\rho}$) via MRF dictionary D
- Formulates Eq. (1) as a HQS problem with a DDM prior⁵.
- Solves following ADMM (Algorithm 1)
- Outputs reconstructed MRF images $\mathbf{x}_{rec}$ and parameter maps $\mathbf{q}_{rec}$.

SOLUTION: OUR CONTRIBUTION

MRF-DiPh, an MRF reconstruction method:

- based on DDM approaches
- conditioned on low-quality reconstructions
- guided at sampling by the physics of the model by
 - k-space (measurement) consistency
 - Bloch equations

Algorithm 1 MRF-DiPh

Require: $f, \epsilon_\theta, \{t_k\}_{k=1}^K, \{\bar{\alpha}_{t_k}\}_{k=1}^K, \lambda, \tau, \xi$

- 1: Set $\sigma_k^2 := (1 - \bar{\alpha}_{t_k})/\bar{\alpha}_{t_k}$, $\mu_k := \lambda/\sigma_k^2$, $\gamma_k := \tau\mu_k$
- 2: Initialize $\mathbf{x}_K \sim \mathcal{N}(\mathbf{0}, \mathbf{Id})$, $\mathbf{z}_K = \mathbf{v}_K = \mathbf{0}$
- 3: **for** $k = K, \dots, 1$ **do**
- 4: $\tilde{\mathbf{x}}_{0,k} = (1/\sqrt{\bar{\alpha}_{t_k}}) (\mathbf{x}_k - \sqrt{1 - \bar{\alpha}_{t_k}} \epsilon_\theta(\mathbf{x}_k, t_k, \mathbf{x}_c))$
- 5: $\hat{\mathbf{x}}_{0,k} = \text{prox}_{\frac{1}{\mu_k + \gamma_k} f} \left(\frac{\mu_k \tilde{\mathbf{x}}_{0,k} + \gamma_k \mathbf{z}_{k-1} - \mathbf{v}_k}{\mu_k + \gamma_k} \right)$
- 6: $(\mathbf{z}_{k-1}, \mathbf{q}_{k-1}) \leftarrow \text{DICT-MATCH}(\hat{\mathbf{x}}_{0,k} + \mathbf{v}_k/\gamma_k)$
- 7: $\mathbf{v}_{k-1} = \mathbf{v}_k + \gamma_k (\hat{\mathbf{x}}_{0,k} - \mathbf{z}_{k-1})$
- 8: $\hat{\epsilon}_k = (1/\sqrt{1 - \bar{\alpha}_{t_k}}) (\mathbf{x}_k - \sqrt{\bar{\alpha}_{t_k}} \mathbf{z}_{k-1})$
- 9: $\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{Id})$
- 10: $\mathbf{x}_{k-1} = \sqrt{\bar{\alpha}_{t_{k-1}}} \mathbf{z}_{k-1} + \sqrt{1 - \bar{\alpha}_{t_{k-1}}} (\sqrt{\xi} \epsilon + \sqrt{1 - \xi} \hat{\epsilon}_k)$
- 11: **end for**; **return** $\mathbf{x}_{rec} = \mathbf{z}_0$, $\mathbf{q}_{rec} = \mathbf{q}_0 := \{\mathbf{T1}_0, \mathbf{T2}_0, \boldsymbol{\rho}_0\}$

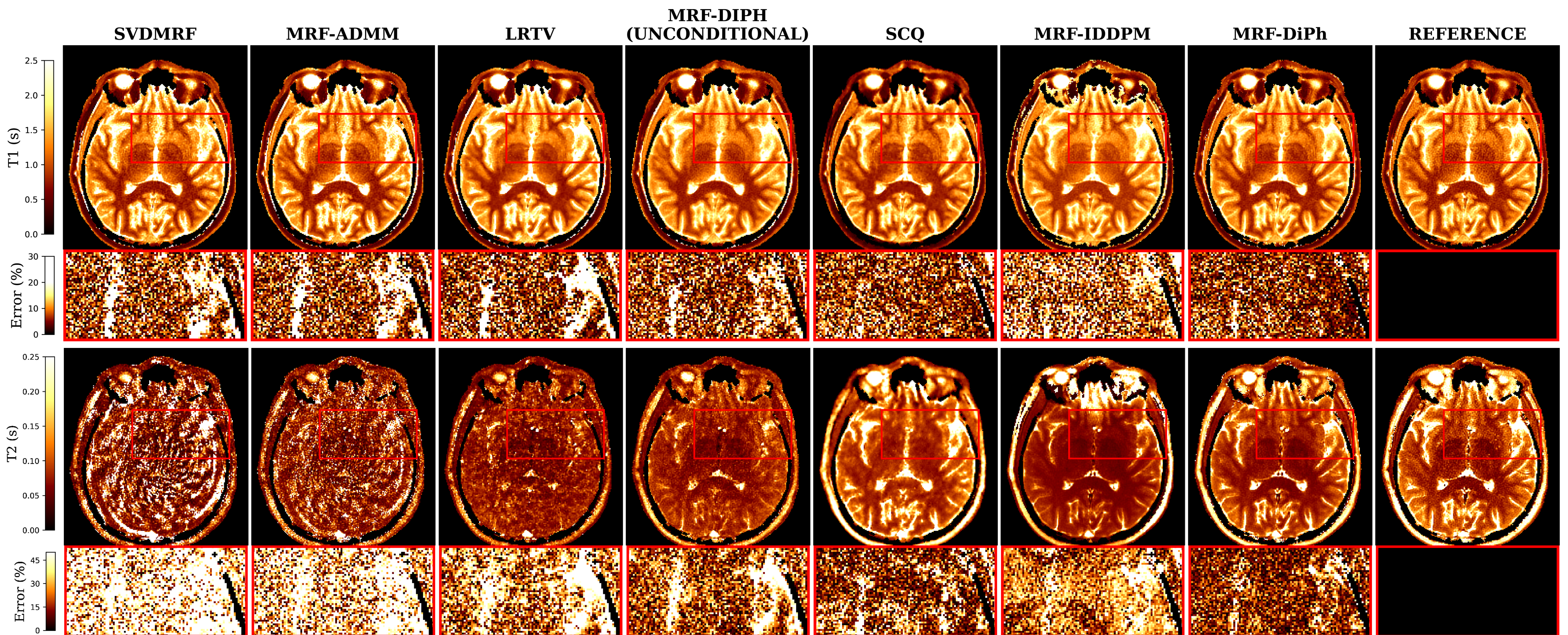


Figure 1. Reconstructions of T1 and T2 maps for the assessed approaches on data with acceleration factor of 5

Table 1. Metrics for reconstructions of T1/T2 maps from accelerated k-space data (R=5)

Method	MAPE (%)		NRMSE	
	T1	T2	TSMI	k-space
SVD-MRF	20.01	144.27	57.10	99.93
MRF-ADMM	20.30	68.51	30.90	18.69
LRTV	19.84	39.01	37.95	11.72
SCQ	8.76	22.61	--	--
MRF-IDDP	8.45	22.54	27.26	36.06
MRF-DiPh (base)	6.75	18.40	18.65	22.82
MRF-DiPh (A)	6.80	18.41	18.70	22.52
MRF-DiPh (B)	7.15	18.63	18.64	22.40
MRF-DiPh (C)	7.17	18.82	18.79	22.12
MRF-DiPh (D)	11.32	29.78	25.36	19.17

Table 2. MRF-DiPh reconstruction time vs. accuracy for various sampling steps (K) and maximum CG iterations. Results are for test image in Figure 1.

MRF-DiPh	Base	K				CG		
		5	10	20	50	1	10	20
Runtime (s)	44.17	8.83	15.88	30.03	72.29	30.02	61.03	91.79
TSMI NRMSE	15.76	16.74	14.99	15.55	16.06	15.73	15.87	15.70
(T1 + T2)/2 MAPE	10.42	14.20	11.93	10.62	10.22	10.37	10.45	10.33

REFERENCES

1. D. Ma et al., Nature, 2013; 2. Ho et al., Advances in Neural Information Processing Systems, 2020; 3. Nichol et al., International Conference in Machine Learning, 2021; 4. Dhariwal and Nichol, Advances in Neural Information Processing Systems, 2021; 5. Boyd et al., Foundations and Trends® in Machine Learning, 2011; 6. D. McGivney, et al. IEEE transactions on medical imaging, 2014; 7. Aslander et al., Magnetic Resonance in Medicine, 2018; 8. Golbabaee et al., Medical Image Analysis, 2021; 9. Fang et al., IEEE Transactions on Medical Imaging, 2019; 10. Mayo et al. arXiv preprint, 2024;

NUMERICAL EXPERIMENTS

- 8 subjects, 15 axial slices each (train/test split = 75%/25%)
- Acceleration factor R=5 simulated on k-space
- Reference from unaccelerated, densely-sampled acquisitions
- Benchmarks: SVD-MRF⁶, MRF-ADMM⁷, LRTV⁸, SCQ⁹, and MRF-IDDP¹⁰
- Ablation studies: $\xi = 0.5$ (**mode A**), $\xi = 0.0$ (**mode B**), MRF-DiPh w/o DICT-MATCH (**mode C**) and unconditional DDM w/ physics guidance (**mode D**)

RESULTS & DISCUSSION

- **MRF-DiPh ★★★★★** | MRF-IDDP ★★★★★ | CNN ★★★★★ | LRTV ★★★★★ | MRF-ADMM ★★★★★ | SVD-MRF ★★★★★
- MRF-DiPh:
 - = lower errors (Tab. 1) + more defined anatomies (Fig. 1)
 - >> MRF-DiPh w/o DICT-MATCH (Mode C).
- Data-driven >> Unconditional MRF-DiPh (Mode D) >> Classical
- ↓ errors + ↑ reliability = DDM prior + Physics Guidance = MRF-DiPh